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| **Robotic Exoskeleton** | | | | |
| In the second half of the 20th century, the development of robotic exoskeletons was began.  Because of the technical limitations of their time, and the lack of experience and knowledge, it still took several decades until the technology matured and the first exoskeletons were ready for the market.  With the beginning of the 21st century, the first exoskeleton products made their way to the market and are accessible to an increasing number of users. One of the first applications was gait rehabilitation in stroke and spinal cord injured patients. | | | | |
| **YEAR** | **PLACE** | **EXOSKELETON** | **TYPE** | **APPLICATION** |
| At the end of the 1960s | Mihajlo Pupin Institute, Serbia. | **-** | Gait assistance | Exoskeletons for gait assistance. |
| Around 1965 | General Electric, US. | Hardiman | Large full-body exoskeleton | Designed to augment the user’s strength to enable the lifting of heavy objects. |
| Early 1970s | University of Wisconsin-Madison, US. | - | - | - |
| 2001 | - | - | Gait rehabilitation | First applications was gait rehabilitation in stroke and spinal cord injured patients. used in hospitals and rehabilitation centers worldwide. |